## GUIDED NOTES (MODEL NOTES)

## Vocabulary

- transformation: a function (rule) that changes the figure in some way.
- translation: a type of transformation where every point of a figure is moved the same distance in the same direction; the figure slides without rotating or flipping.
- preimage: the original figure, before any transformation(s); the input.
- image: the final figure; the result from applying the transformation(s); the output.
- rigid motion: a transformation where the image is congruent to the preimage; a translation is an example of rigid motion.

- vector: a path, with a starting and ending point that a figure follows; it has size (magnitude/distance) and direction.
- example: $\overrightarrow{M N}$, read "vector $M N$, " where $M$ is the starting (initial) point and $N$ is the ending (terminal) point


We can also represent $\overrightarrow{M N}$ in its component
form: $\langle 4,-2\rangle$, where 4 is the horizontal component, and -2 is the vertical component.

## Example Problems

1) Complete the table below for the unshaded preimage and shaded image.

2) Polygon $A B C D E$ has the following vertices: $A(1,-4), B(3,-5), C(5,-3)$,
$D(3,-3)$, and $E(1,1)$. Draw
Polygon $A B C D E$, then translate
Polygon $A B C D E$ using the vector $\langle-5,2\rangle$.
Label Polygon $A B C D E$ and its image.

3) What if the preimage was not on the coordinate plane? How would we construct the image? Construct the image given the following preimage and vector.


## GUIDED NOTES (TEACHER GUIDE)

## Example 3

How to construct a translation with a compass and straightedge.
Step 1: Use the compass to measure the length of
the vector.
Instruction
Step 3: Use the compass to measure the distance
between Point $A$ and the initial end of the
vector. This measurement tells us about the
distance between Point $A^{\prime}$ and the terminal end
of the vector.
Instruction

