Move, Turn Left, and Move Again

Objective:

Program your EV3 robot to move forward, **turn LEFT 90 degrees**, resume moving forward, and then come to a complete stop.

Materials:

- EV3 Robot
- ☐ Chromebook with Mindstorms software

Instructions:

- Using the Mindstorms software on your Chromebook, program your EV3 robot to complete the objective above.
- 2. Document the steps you needed to take to complete your objective with the troubleshooting reflection sheet.

Citation:

Did you find your solution somewhere? If so, please include a citation here!

Example:

Savage, A. (2013, August 13). *Making a Real Life-Size Wall-E Robot (Geek Week!)* Retrieved from https://www.youtube.com/watch?v=7oVSaUWeKt0

Move, Turn Around, and Move Again

Objective:

Program your EV3 robot to move forward, **turn AROUND 180 degrees**, resume moving forward, and then come to a complete stop.

Materials:

- ☐ EV3 Robot
- ☐ Chromebook with Mindstorms software

Instructions:

- Using the Mindstorms software on your Chromebook, program your EV3 robot to complete the objective above.
- 2. Document the steps you needed to take to complete your objective with the troubleshooting reflection sheet.

Citation:

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Drive Completely Around an Obstacle

Objective:

Program your EV3 robot to **drive around an obstacle using only 90 degree turns**. To successfully complete this task, the robot must completely turn around all four sides of your object.

Materials:

- ☐ EV3 Robot
- ☐ Chromebook with Mindstorms software

Instructions:

- Using the Mindstorms software on your Chromebook, program your EV3 robot to complete the objective above.
- 2. Document the steps you needed to take to complete your objective with the troubleshooting reflection sheet.

Citation:

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